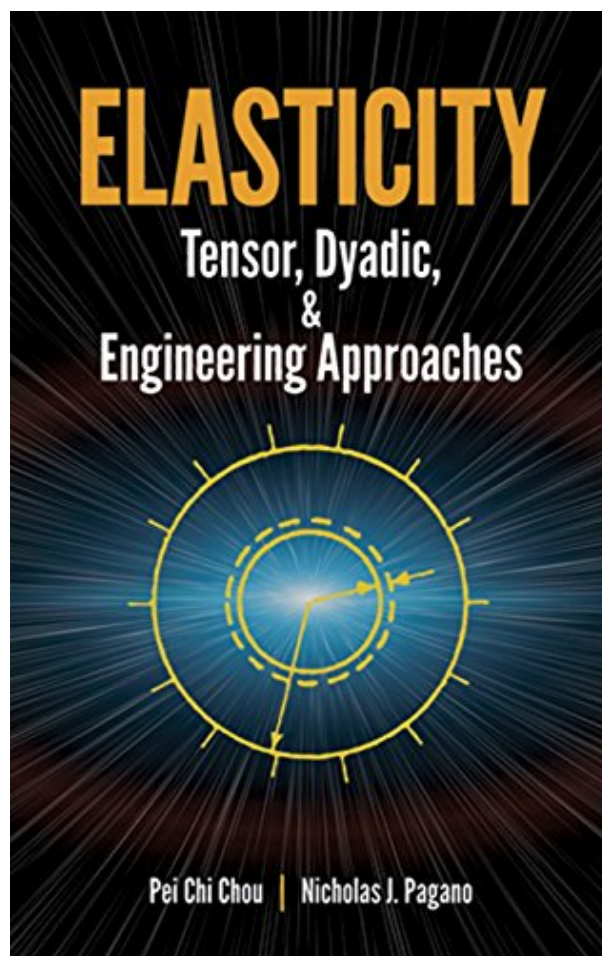
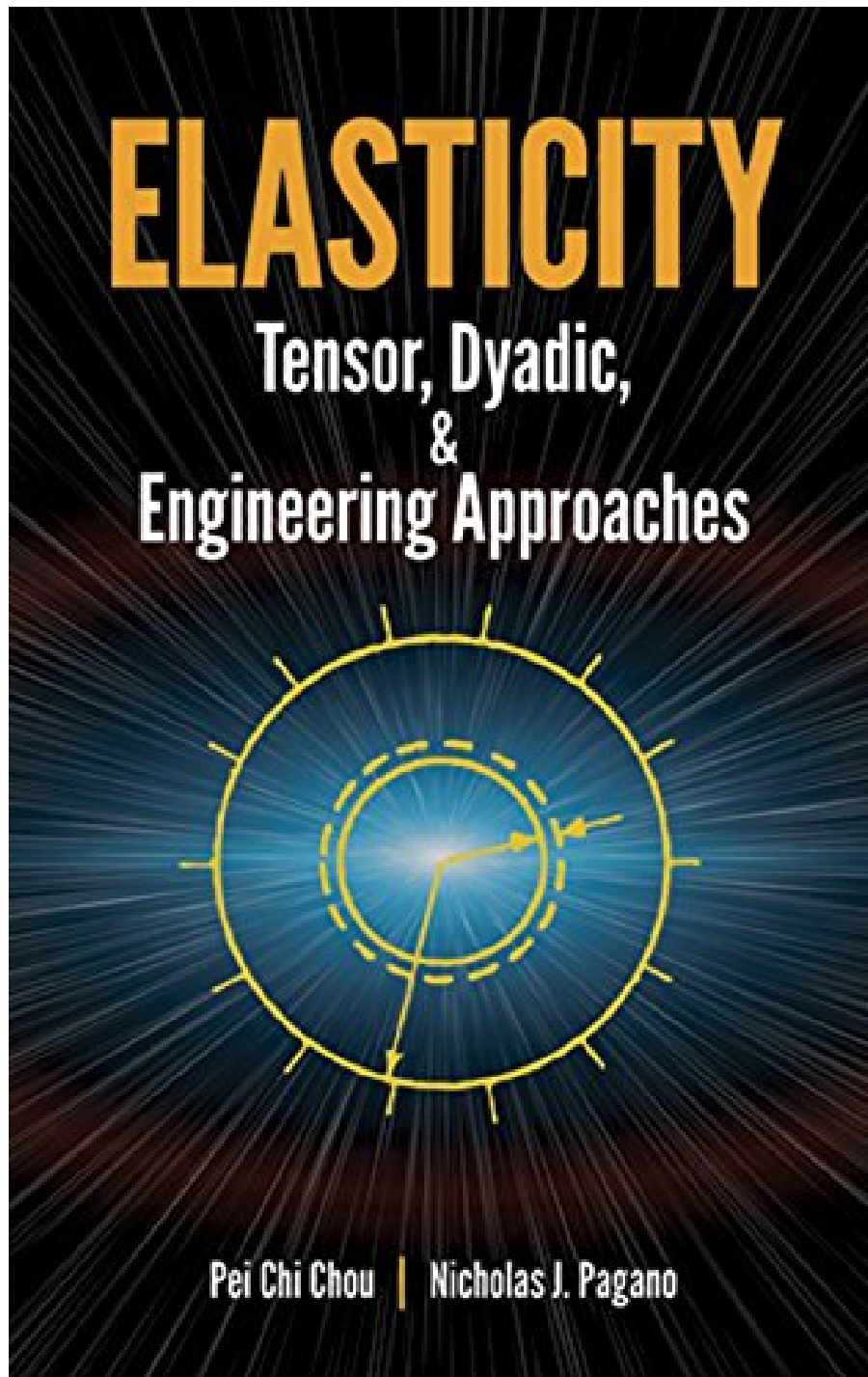


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Written for advanced undergraduates and beginning graduate students, this exceptionally clear text treats both the engineering and mathematical aspects of elasticity. It is especially useful because it offers the theory of linear elasticity from three standpoints: engineering, Cartesian tensor, and vector-dyadic. In this way the student receives a more complete picture and a more thorough understanding of engineering elasticity. Prerequisites are a working knowledge of statics and strength of materials plus calculus and vector analysis. The first part of the book treats the theory of elasticity by the most elementary approach, emphasizing physical significance and using engineering notations. It gives engineering students a clear, basic understanding of linear elasticity. The latter part of the text, after Cartesian tensor and dyadic notations are introduced, gives a more general treatment of elasticity. Most of the equations of the earlier chapters are repeated in Cartesian tensor notation and again in vector-dyadic notation. By having access to this threefold approach in one book, beginning students will benefit from cross-referencing, which makes the learning process easier. Another helpful feature of this text is the charts and tables showing the logical relationships among the equations--especially useful in elasticity, where the mathematical chain from definition and concept to application is often long. Understanding of the theory is further reinforced by extensive problems at the end of each chapter.

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good review, good intro from another field

By Kris

This book concisely goes through the derivations of elasticity; it is well written and relatively easy to read for a textbook. The numerous tables and flowcharts make this book a very good quick look up reference.

As I am coming at elasticity from another background, I found that a quick review of this book allows me to read and understand papers in this field much more clearly.

The "rosetta stone" table for tensor and vector/dyadic notation of common operators in one of the later chapters is quite useful. I don't think I have seen that spelled out anywhere else. Most books just use one convention or the other.

Another two good background chapters are the summary of the introduction of Jeffrey's Cartesian Tensors book and a chapter summarizing formulas from general curvilinear coordinates.

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